

# Solutions to the problems of the 5-th International Physics Olympiad, 1971, Sofia, Bulgaria

*The problems and the solutions are adapted by  
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Reference: O. F. Kabardin, V. A. Orlov, in “International Physics Olympiads for High School Students”, eds. V. G. Razumovski, Moscow, Nauka, 1985. (In Russian).

## Theoretical problems

### Question 1.

The blocks slide relative to the prism with accelerations  $\mathbf{a}_1$  and  $\mathbf{a}_2$ , which are parallel to its sides and have the same magnitude  $a$  (see Fig. 1.1). The blocks move relative to the earth with accelerations:

$$(1.1) \quad \mathbf{w}_1 = \mathbf{a}_1 + \mathbf{a}_0;$$

$$(1.2) \quad \mathbf{w}_2 = \mathbf{a}_2 + \mathbf{a}_0.$$

Now we project  $\mathbf{w}_1$  and  $\mathbf{w}_2$  along the  $x$ - and  $y$ -axes:

$$(1.3) \quad w_{1x} = a \cos \alpha_1 - a_0;$$

$$(1.4) \quad w_{1y} = a \sin \alpha_1;$$

$$(1.5) \quad w_{2x} = a \cos \alpha_2 - a_0;$$

$$(1.6) \quad w_{2y} = -a \sin \alpha_2.$$

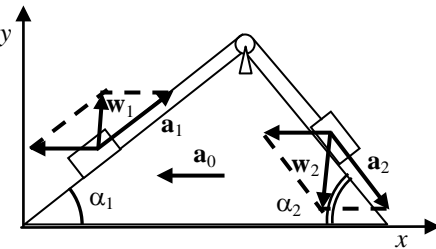


Fig. 1.1

The equations of motion for the blocks and for the prism have the following vector forms (see Fig. 1.2):

$$(1.7) \quad m_1 \mathbf{w}_1 = m_1 \mathbf{g} + \mathbf{R}_1 + \mathbf{T}_1;$$

$$(1.8) \quad m_2 \mathbf{w}_2 = m_2 \mathbf{g} + \mathbf{R}_2 + \mathbf{T}_2;$$

$$(1.9) \quad M \mathbf{a}_0 = M \mathbf{g} - \mathbf{R}_1 - \mathbf{R}_2 + \mathbf{R} - \mathbf{T}_1 - \mathbf{T}_2.$$

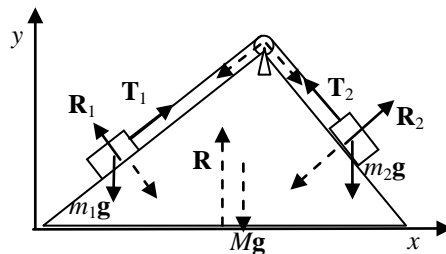


Fig. 1.2

The forces of tension  $\mathbf{T}_1$  and  $\mathbf{T}_2$  at the ends of the thread are of the same magnitude  $T$  since the masses of the thread and that of the pulley are negligible. Note that in equation (1.9) we account for the net force  $-(\mathbf{T}_1 + \mathbf{T}_2)$ , which the bended thread exerts on the

prism through the pulley. The equations of motion result in a system of six scalar equations when projected along  $x$  and  $y$ :

$$(1.10) \quad m_1 a \cos \alpha_1 - m_1 a_0 = T \cos \alpha_1 - R_1 \sin \alpha_1 ;$$

$$(1.11) \quad m_1 a \sin \alpha_1 = T \sin \alpha_1 + R_1 \cos \alpha_1 - m_1 g ;$$

$$(1.12) \quad m_2 a \cos \alpha_2 - m_2 a_0 = -T \cos \alpha_2 + R_2 \sin \alpha_2 ;$$

$$(1.13) \quad m_2 a \sin \alpha_2 = T \sin \alpha_2 + R_2 \cos \alpha_2 - m_2 g ;$$

$$(1.14) \quad -M a_0 = R_1 \sin \alpha_1 - R_2 \sin \alpha_2 - T \cos \alpha_1 + T \cos \alpha_2 ;$$

$$(1.15) \quad 0 = R - R_1 \cos \alpha_1 - R_2 \cos \alpha_2 - M g .$$

By adding up equations (1.10), (1.12), and (1.14) all forces internal to the system cancel each other. In this way we obtain the required relation between accelerations  $a$  and  $a_0$ :

$$(1.16) \quad a = a_0 \frac{M + m_1 + m_2}{m_1 \cos \alpha_1 + m_2 \cos \alpha_2} .$$

The straightforward elimination of the unknown forces gives the final answer for  $a_0$ :

$$(1.17) \quad a_0 = \frac{(m_1 \sin \alpha_1 - m_2 \sin \alpha_2)(m_1 \cos \alpha_1 + m_2 \cos \alpha_2)}{(m_1 + m_2 + M)(m_1 + m_2) - (m_1 \cos \alpha_1 + m_2 \cos \alpha_2)^2} .$$

It follows from equation (1.17) that the prism will be in equilibrium ( $a_0 = 0$ ) if:

$$(1.18) \quad \frac{m_1}{m_2} = \frac{\sin \alpha_2}{\sin \alpha_1} .$$

## Question 2.

We will denote by  $H$  ( $H = \text{const}$ ) the height of the tube above the mercury level in the pan, and the height of the mercury column in the tube by  $h_i$ . Under conditions of mechanical equilibrium the hydrogen pressure in the tube is:

$$(2.1) \quad P_{H_2} = P_{\text{air}} - \rho g h_i ,$$

where  $\rho$  is the density of mercury at temperature  $t_i$ :

$$(2.2) \quad \rho = \rho_0 (1 - \beta t)$$

The index  $i$  enumerates different stages undergone by the system,  $\rho_0$  is the density of mercury at  $t_0 = 0$  °C, or  $T_0 = 273$  K, and  $\beta$  its coefficient of expansion. The volume of the hydrogen is given by:

$$(2.3) \quad V_i = S(H - h_i) .$$

Now we can write down the equations of state for hydrogen at points 0, 1, 2, and 3 of the  $PV$  diagram (see Fig. 2):

$$(2.4) \quad (P_0 - \rho_0 g h_0) S(H - h_0) = \frac{m}{M} R T_0 ;$$

$$(2.5) \quad (P_1 - \rho_0 g h_1) S(H - h_1) = \frac{m}{M} R T_0 ;$$

$$(2.6) \quad (P_2 - \rho_1 g h_2) S(H - h_2) = \frac{m}{M} R T_2 ,$$

where  $P_2 = \frac{P_1 T_2}{T_0}$ ,  $\rho_1 = \frac{\rho_0}{1 + \beta(T_2 - T_0)} \approx \rho_0 [1 - \beta(T_2 - T_0)]$  since the process 1–3 is

isochoric, and:

$$(2.7) \quad (P_2 - \rho_2 g h_3) S (H - h_3) = \frac{m}{M} R T_3$$

where  $\rho_2 \approx \rho_0 [1 - \beta(T_3 - T_0)]$ ,  $T_3 = T_2 \frac{V_3}{V_2} = T_2 \frac{H - h_3}{H - h_2}$  for the isobaric process 2–3.

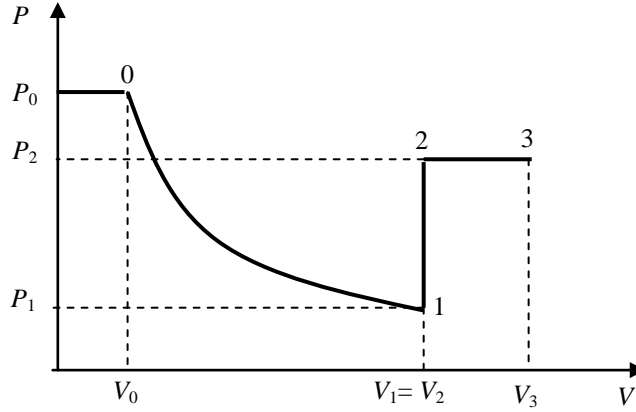


Fig. 2

After a good deal of algebra the above system of equations can be solved for the unknown quantities, an exercise, which is left to the reader. The numerical answers, however, will be given for reference:

$$\begin{aligned} H &\approx 1.3 \text{ m;} \\ m &\approx 2.11 \times 10^{-6} \text{ kg;} \\ T_2 &\approx 364 \text{ K;} \\ P_2 &\approx 1.067 \times 10^5 \text{ Pa;} \\ T_3 &\approx 546 \text{ K;} \\ P_2 &\approx 4.8 \times 10^4 \text{ Pa.} \end{aligned}$$

### Question 3.

A circuit equivalent to the given one is shown in Fig. 3. In a steady state (the capacitors are completely charged already) the same current  $I$  flows through all the resistors in the closed circuit A B F G H D A. From the Kirchhoff's second rule we obtain:

$$(3.1) \quad I = \frac{E_4 - E_1}{4R}.$$

Next we apply this rule for the circuit ABCDA:

$$(3.2) \quad V_1 + IR = E_2 - E_1,$$

where  $V_1$  is the potential difference across the capacitor  $C_1$ . By using the expression (3.1) for  $I$ , and the equation (3.2) we obtain:

$$(3.3) \quad V_1 = E_2 - E_1 - \frac{E_4 - E_1}{4} = 1 \text{ V.}$$

Similarly, we obtain the potential differences  $V_2$  and  $V_4$  across the capacitors  $C_2$  and  $C_4$  by considering circuits BFGCB and FGHEF:

$$(3.4) \quad V_2 = E_4 - E_2 - \frac{E_4 - E_1}{4} = 5 \text{ V,}$$

$$(3.5) \quad V_4 = E_4 - E_3 - \frac{E_4 - E_1}{4} = 1 \text{ V}.$$

Finally, the voltage  $V_3$  across  $C_3$  is found by applying the Kirchhoff's rule for the outermost circuit EHDAH:

$$(3.6) \quad V_3 = E_3 - E_1 - \frac{E_4 - E_1}{4} = 5 \text{ V}.$$

The total energy of the capacitors is expressed by the formula:

$$(3.7) \quad W = \frac{C}{2} (V_1^2 + V_2^2 + V_3^2 + V_4^2) = 26 \mu\text{J}.$$

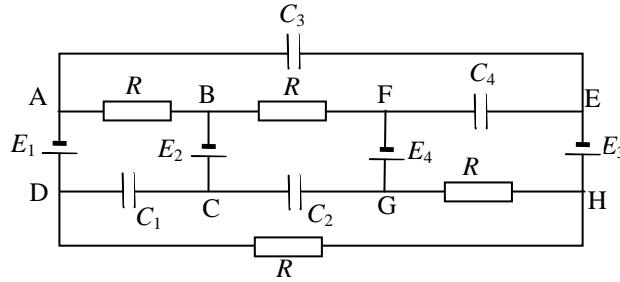


Fig. 3

When points B and H are short connected the same electric current  $I'$  flows through the resistors in the BFGH circuit. It can be calculated, again by means of the Kirchhoff's rule, that:

$$(3.8) \quad I' = \frac{E_4}{2R}.$$

The new steady-state voltage on  $C_2$  is found by considering the BFGCB circuit:

$$(3.9) \quad V_2' + I'R = E_4 - E_2$$

or finally:

$$(3.10) \quad V_2' = \frac{E_4}{2} - E_2 = 0 \text{ V}.$$

Therefore the charge  $q_2'$  on  $C_2$  in the new steady state is zero.

#### Question 4.

In a small time interval  $\Delta t$  the fish moves upward, from point A to point B, at a small distance  $d = v\Delta t$ . Since the glass wall is very thin we can assume that the rays leaving the aquarium refract as if there was water – air interface. The divergent rays undergoing one single refraction, as show in Fig. 4.1, form the first, virtual, image of the fish. The corresponding vertical displacement  $A_1B_1$  of that image is equal to the distance  $d_1$  between the optical axis  $a$  and the ray  $b_1$ , which leaves the aquarium parallel to  $a$ . Since distances  $d$  and  $d_1$  are small compared to  $R$  we can use the small-angle approximation:  $\sin\alpha \approx \tan\alpha \approx \alpha$  (rad). Thus we obtain:

$$(4.1) \quad d_1 \approx R \alpha;$$

$$(4.2) \quad d \approx R \gamma;$$

$$(4.3) \quad \alpha + \gamma = 2\beta;$$

$$(4.4) \quad \alpha \approx n\beta.$$

From equations (4.1) - (4.4) we find the vertical displacement of the first image in terms of  $d$ :

$$(4.5) \quad d_1 = \frac{n}{2-n} d ,$$

and respectively its velocity  $v_1$  in terms of  $v$ :

$$(4.6) \quad v_1 = \frac{n}{2-n} v = 2v .$$

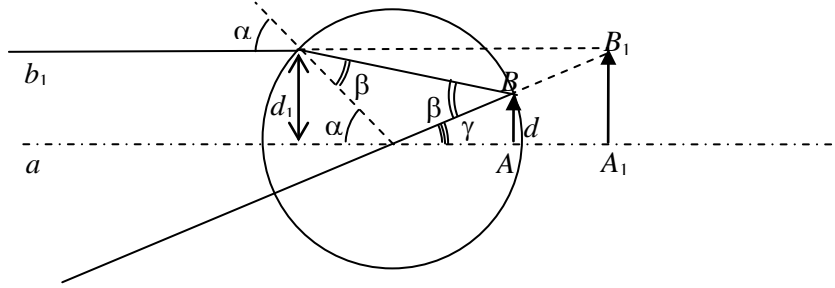


Fig. 4.1

The rays, which are first reflected by the mirror, and then are refracted twice at the walls of the aquarium form the second, real image (see Fig. 4.2). It can be considered as originating from the mirror image of the fish, which move along the line  $A'B'$  at exactly the same distance  $d$  as the fish do.

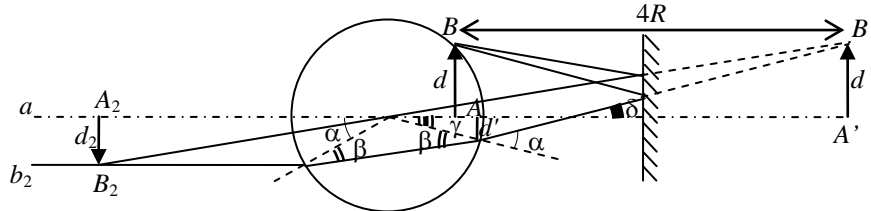


Fig. 4.2

The vertical displacement  $A_2B_2$  of the second image is equal to the distance  $d_2$  between the optical axis  $a$  and the ray  $b_2$ , which is parallel to  $a$ . Again, using the small-angle approximation we have:

$$(4.7) \quad d' \approx 4R\delta - d ,$$

$$(4.8) \quad d_2 \approx R\alpha$$

Following the derivation of equation (4.5) we obtain:

$$(4.9) \quad d_2 = \frac{n}{2-n} d' .$$

Now using the exact geometric relations:

$$(4.10) \quad \delta = 2\alpha - 2\beta$$

and the Snell's law (4.4) in a small-angle limit, we finally express  $d_2$  in terms of  $d$ :

$$(4.11) \quad d_2 = \frac{n}{9n-10} d ,$$

and the velocity  $v_2$  of the second image in terms of  $v$ :

$$(4.12) \quad v_2 = \frac{n}{9n-10} v = \frac{2}{3} v .$$

The relative velocity of the two images is:

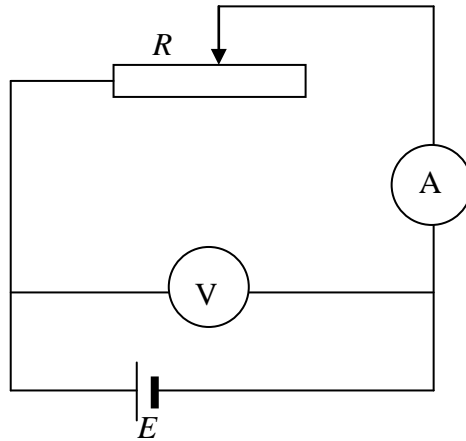
$$(4.13) \quad \mathbf{v}_{\text{rel}} = \mathbf{v}_1 - \mathbf{v}_2$$

in a vector form. Since vectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are oppositely directed (one of the images moves upward, the other, downward) the magnitude of the relative velocity is:

$$(4.14) \quad v_{\text{rel}} = v_1 + v_2 = \frac{8}{3} v .$$

### Experimental problem

The circuit is given in the figure below:

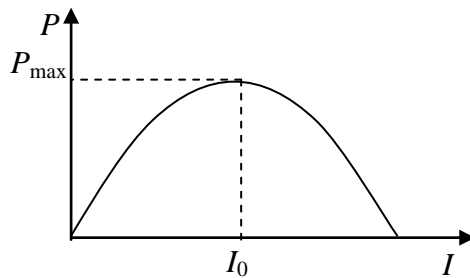


Sliding the contact along the rheostat sets the current  $I$  supplied by the source. For each value of  $I$  the voltage  $U$  across the source terminals is recorded by the voltmeter. The power dissipated in the rheostat is:

$$P = UI$$

provided that the heat losses in the internal resistance of the ammeter are negligible.

1. A typical  $P$ – $I$  curve is shown below:



If the current varies in a sufficiently large interval a maximum power  $P_{\max}$  can be detected at a certain value,  $I_0$ , of  $I$ . Theoretically, the  $P(I)$  dependence is given by:

$$(5.1) \quad P = EI - I^2 r,$$

where  $E$  and  $r$  are the EMF and the internal resistance of the dc source respectively. The maxim value of  $P$  therefore is:

$$(5.2) \quad P_{\max} = \frac{E^2}{4r},$$

and corresponds to a current:

$$(5.3) \quad I_0 = \frac{E}{2r}.$$

2. The internal resistance is determined trough (5.2) and (5.3) by recording  $P_{\max}$  and  $I_0$  from the experimental plot:

$$r = \frac{P_{\max}}{I_0^2}.$$

3. Similarly, EMF is calculated as:

$$E = \frac{2P_{\max}}{I_0}.$$

4. The current depends on the resistance of the rheostat as:

$$I = \frac{E}{R + r}.$$

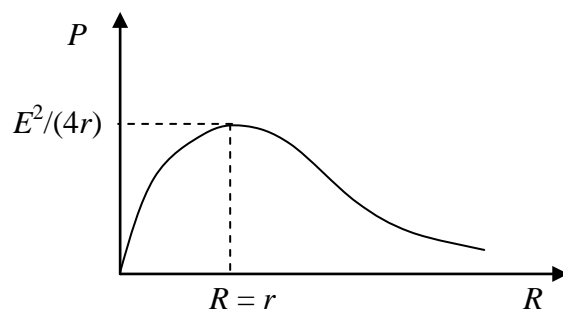
Therefore a value of  $R$  can be calculated for each value of  $I$ :

$$(5.4) \quad R = \frac{E}{I} - r.$$

The power dissipated in the rheostat is given in terms of  $R$  respectively by:

$$(5.5) \quad P = \frac{E^2 R}{(R + r)^2}.$$

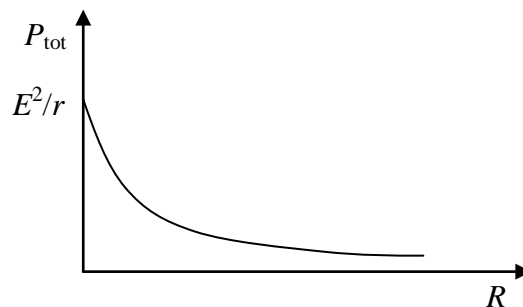
The  $P$ – $R$  plot is given below:



Its maximum is obtained at  $R = r$ .

5. The total power supplied by the dc source is:

$$(5.6) \quad P_{\text{tot}} = \frac{E^2}{R + r}.$$



6. The efficiency respectively is:

(5.7)  $\eta = \frac{P}{P_{tot}} = \frac{R}{R+r}.$

